

Operating Systems

RIOT: An Open OS for an Open IoT

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Agenda

- Internet of Things
- Software for Low-End IoT Devices
- Case Study: RIOT
- RIOT Community

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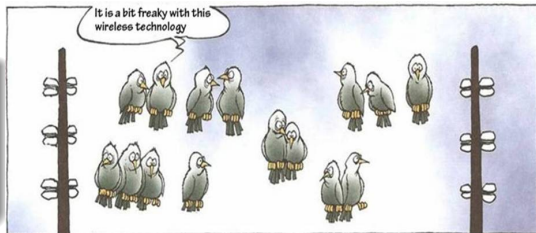
The Evolution of the IoT

Three Disruptive Technologies as
the Roots of the IoT

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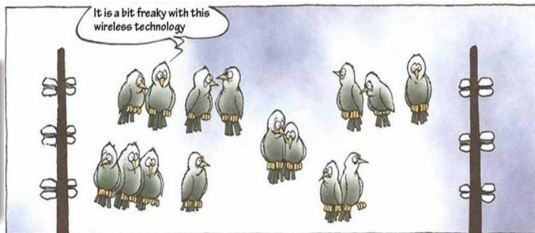
- Wireless Communication



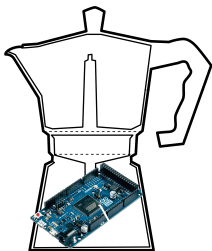
The Evolution of the IoT

Three Disruptive Technologies as the Roots of the IoT

- Wireless Communication
- Low-cost Embedded Systems



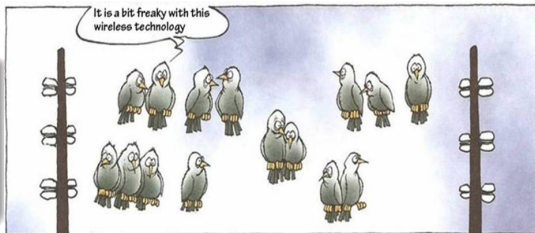
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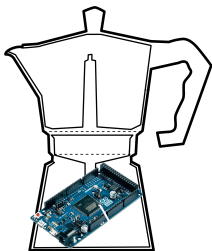
The Evolution of the IoT

Three Disruptive Technologies as the Roots of the IoT

- Wireless Communication
- Low-cost Embedded Systems
- The Internet



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Smart Object Networking at Internet-Scale

Connecting the Physical World with the Internet

- Transforming Things into Smart Objects
- Enabling Interconnected Smart Services

Smart Object Networking at Internet-Scale

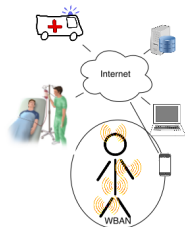
Industrial Automation



Connecting the Physical World with the Internet

- Transforming Things into Smart Objects
- Enabling Interconnected Smart Services

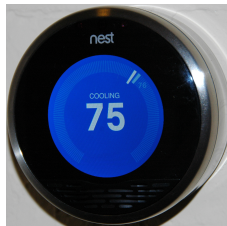
Mobile Health



Micro & Nano Satellites



Building & Home Automation



Use Case Requirements

- Interoperability
- Energy Efficiency
- Reliability
- Latency
- Low Cost Factor
- Autonomy
- Security
- Scalability



It ain't smart if I have to charge it every day.

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Requirements for IoT Software

Low-end IoT Devices: Limited Resources (RFC7228)

iotlab-m3

Senslab
WSN430

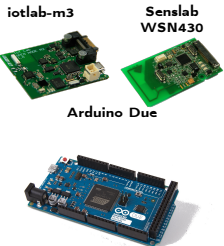
Arduino Due



- Memory < 1 Mb
- CPU < 100 MHz
- Energy < 10 Wh

Requirements for IoT Software

Low-end IoT Devices: Limited Resources (RFC7228)



- Memory < 1 Mb
 - CPU < 100 MHz
 - Energy < 10 Wh
- +
- Use Case Requirements**

=

Software Requirements

- Energy Efficiency
- Sustainability
- Network Connectivity
- Real-Time Capabilities
- Small Memory Footprint
- Security and Safety
- Support for Heterogeneous Hardware

Embedded Operating Systems

No User Interaction

- No GUI required \Rightarrow No Pseudo-Parallel Execution is required
- Must Operate Autonomously \rightarrow Must Recover from Errors
- Autoconfiguration is required



Source: Embedded Lab, <https://www.electronics-lab.com/>

Embedded Operating Systems

- ### No User Interaction
- No GUI required ⇒ No Pseudo-Parallel Execution is required
 - Must Operate Autonomously → Must Recover from Errors
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- ### Constrained Hardware
- Often no MMU¹ and no FPU²
 - Typically no Display or Input Devices
 - In many cases no Persistent Memory



Source: Embedded Lab, <https://www.electronics-lab.com/>

¹Memory Management Unit
²Floating Point Unit

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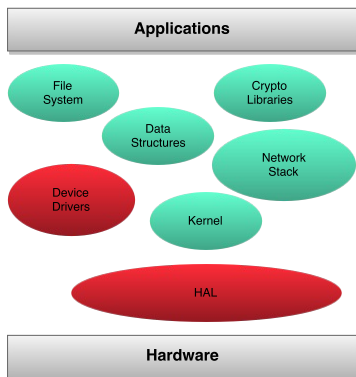
- No Multi-User Support required
- Often only one Application
- Typically no dynamic linking \rightarrow just one statically linked binary

¹Memory Management Unit

²Floating Point Unit

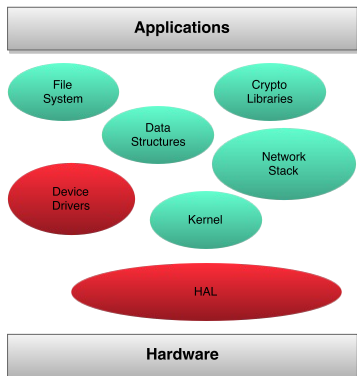
The Need for an OS for Low-end IoT Devices

Unified Software Platform



The Need for an OS for Low-end IoT Devices

Unified Software Platform



Open Source



Operating Systems for Low-End IoT Devices: Linux

Full-fledged OS



- Too Big
- Requires a MMU
- Not Targeted for Real-Time or Low-Energy

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WSN OS



- Hard to Learn
- No System Level Compatibility

Operating Systems for Low-End IoT Devices: Linux

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WSN OS



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RTOS



- No Built in Networking Support
- No Common API

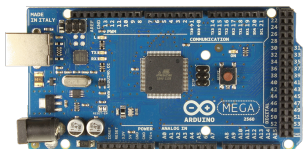
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The friendly OS for the IoT

"If your IoT device cannot run Linux, then use RIOT!"

- RIOT requires only a few kB of RAM/ROM, and a small CPU
- With RIOT, code once & run heterogeneous IoT hardware
 - 8bit hardware (e.g. Arduino)
 - 16bit hardware (e.g. MSP430)
 - 32bit hardware (e.g. ARM Cortex-M, x86)



Open Standards, Open Source

- Free, open source (LGPLv2.1) operating system for constrained IoT devices
- Write your code in **ANSI-C** or **C++**
- Compliant with the most widely used POSIX features like pthreads and sockets
- No IoT hardware needed for development
- Run & debug RIOT as native process in Linux



Programming Language and Guidelines

Important Programming Language Properties

- No Overhead
- Full Control over Memory Management
- Direct Access to the Hardware
- Binding to other Languages
- Usability

Why C?

- Ticks all the Boxes
- Stable Specification
- Widely Used → Tooling

```

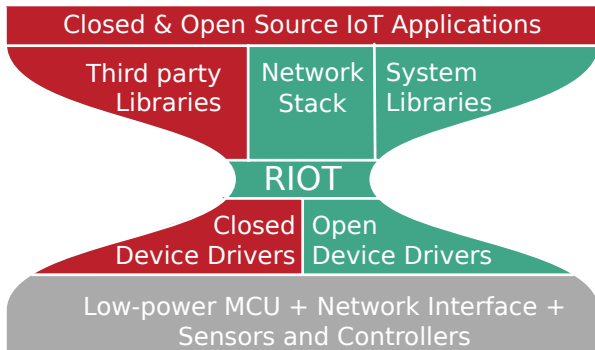
140 void thread_yield(void)
141 {
142     unsigned old_state = irq_disable();
143     thread_t *me = thread_get_active();
144
145     if (me->status >= STATUS_ON_RUNQUEUE) {
146         sched_runq_advance(me->priority);
147     }
148     irq_restore(old_state);
149
150     thread_yield_higher();
151 }

```

Programming Guidelines

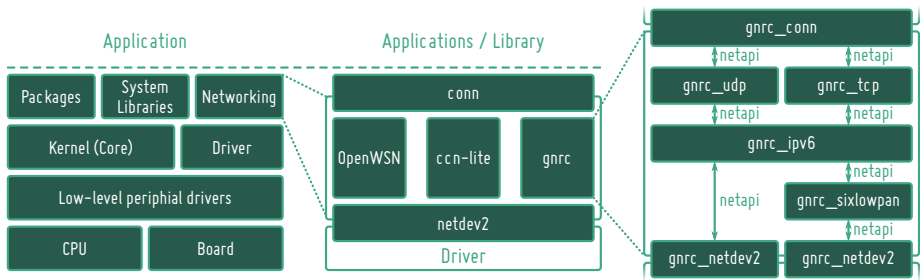
- Follow a Structured and Procedural Approach
- Keep It Simple, Stupid (KISS)
- No Dynamic Memory Allocation
- Be Resource-aware
- No Macro “Magic”

Architectural Overview



- Design Decisions**
- Efficient & Flexible Micro-Kernel
 - System Level Interoperability
 - Networking Interoperability

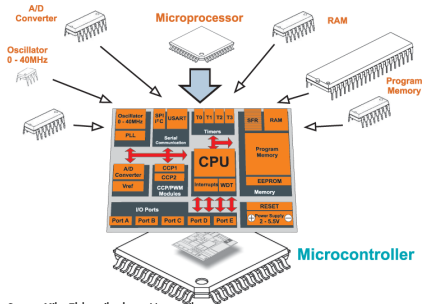
The Structure



Hardware Abstraction Layer (HAL)

Challenge: Support a Plethora of different Platforms

- Different Processor Architectures (8 bit, 16 bit, 32 bit ...)
- Microcontroller¹Peripherals
- Sensors and Actuators
- Network Devices
- Crypto Devices
- ...



Source: MikroElektronika, <https://www.mikroe.com>

Goal: Provide a Common API

- Drivers for MCU Core
- Drivers for MCU Peripherals
- Device Drivers
- Timer API

¹MicroController Unit (MCU)

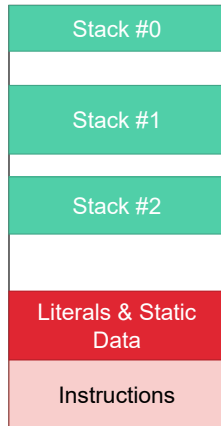
Multi-Threading

- Microkernel approach
 - But no Memory Protection
 - ⇒ Stack Overflows are possible
- Provides Standard Multi-Threading
- Each Thread contains a (minimal) Thread Control Block (TCB)

Low Memory Usage

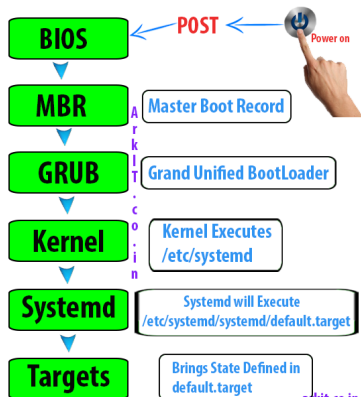
On a Low-end IoT Device (16-bit, 8 MHz):

- Min. TCB: 8 bytes
- Min. Stack Size: 96 bytes
- Up to 16,000 Messages/s
($\hat{=}$ 10,000 Packets/s for 802.15.4)



Boot Sequence

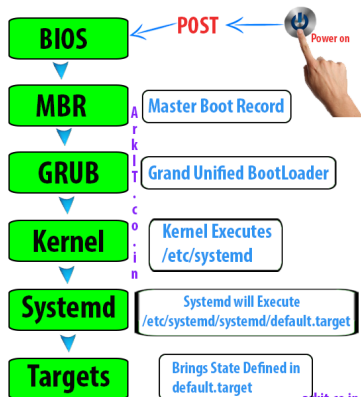
Linux Boot Sequence



Source: <https://arkit.co.in/linux-boot-process-millionaire-guide/>

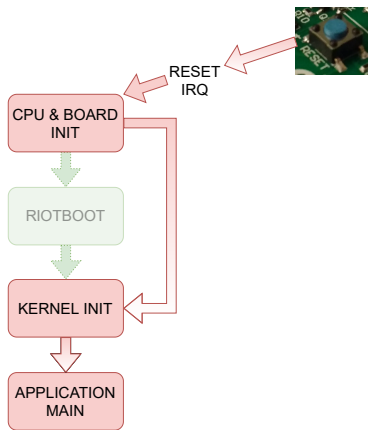
Boot Sequence

Linux Boot Sequence



Source: <https://arkit.co.in/linux-boot-process-millionaire-guide/>

RIOT Boot Sequence



Scheduling

- **Preemptive**
- Threads have fixed **Priorities**
- The Thread in the **Run-Queue** with the **highest Priority** will run

A Periodic System Tick requires Timers

- A running Timer prevent the MCU to enter Deep Sleep Modes
- Periodic Wakeup waste Energy if there is nothing to do



Accounting for Real-Time Requirements

- All Data Structures in the Kernel have Static Size \Rightarrow All Operations are $O(1)$
- The Behavior of the Kernel is completely deterministic
- Interrupt Handlers are as short as possible



Source: Educación Física,

<http://efsancristobalcartagena.blogspot.com>

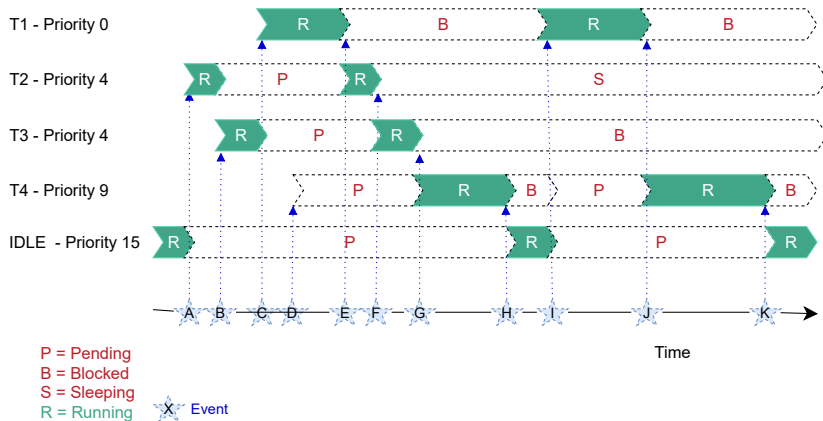
Thread States

- A Thread can have one of the following States:
 - Stopped
 - Sleeping
 - Blocked
 - Running
 - Pending
- The States **Running** and **Pending** indicate that the Thread is on the **Run-Queue**
⇒ The Thread is ready to run

It may be blocked waiting for ...

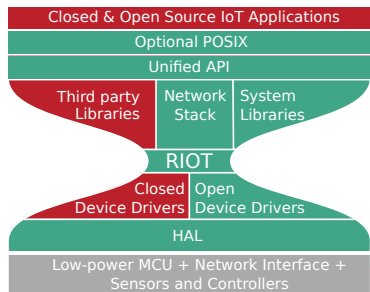
- a mutex
- a message to be received
- a message to be sent
- a response to a previous message
- a thread flag
- an action in its mailbox
- a condition variable

Scheduling example



Application Programming Interface (API)

- Application shall be independent from the Hardware
- Portable Operating System Interface (POSIX) provides a common API among OS
- Not well suited for low-power IoT Devices
 - Origins from the 1980's
 - Not very modern
 - Not tailored for constrained Resources
 - → But facilitates (initial) porting
- A POSIX-like API for this Class of Devices is missing so far



Modularity and Reusability



- Specialized Applications require only a Subset of the available Features
- Fine-grained Modularity is required to reduce the Binary Size
- Kernel Features may be disabled (→ Even Multi-Threading is optional)

```

[NER] | 1 | 2 | 3 | 4 | 5 | 6 |
[Top]
----- RIOT Configuration -----
[ ] Configure RIOT Core ----
Drivers
System -->
Packages -->
External Modules ----
*** RIOT is in a migration phase. ***
*** Some configuration options may not be here. Use CFLAGS instead. ***
[*] Development Help

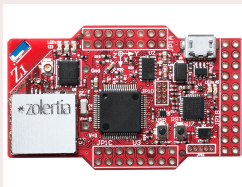
[Space/Enter] Toggle/enter [ESC] Leave menu [S] Save
[O] Load [?] Symbol info [J] Jump to symbol
[F] Toggle show-help mode [C] Toggle show-name mode [A] Toggle show-all mode
[Q] Quit (prompts for save) [D] Save minimal config (advanced)
  
```

Result: Low Porting Effort

- Emulation support: RIOT as a Process
- Third-Party Development Tools
- Third-Party Library Packages

Package	Diff Size	
	Overall	Relative
libcoap	639 lines	6.3 %
libfixmath	34 lines	0.2 %
lwip	767 lines	1.3 %
micro-ecc	14 lines	0.8 %
relic	24 lines	<0.1 %

Memory Comparison



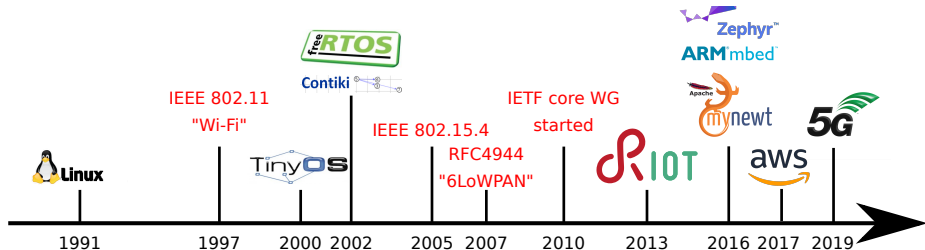
RIOT is as Small as Traditional WSN Operating Systems

Application	ROM	RAM
RIOT 2016.04	52,378	5,618
Contiki 3.0	51,562	5,530
TinyOS tinyos-main	40,574	6,812

Standard IoT IPv6 Networking Application

Code size comparison [Bytes] between RIOT, Contiki, and TinyOS.

Review & Perspectives



IoT Software in 2022

- Most popular IoT OS are:
 - RIOT
 - Zephyr
 - AWS FreeRTOS
- RIOT as the Linux for the IoT?
- ongoing challenges: Cloud integration, security, software updates

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9 Years of RIOT

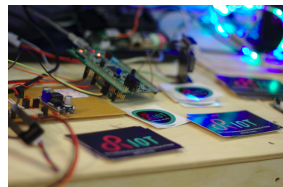
RIOT Open Source Development

- More Than 38,000 Commits and More Than 14,000 Pull Requests
- Over 1,800 forks on GitHub
- More Than 290 Contributors
- Support for More Than 230 Hardware Platforms
- Over 500 Scientific Publications



Get in touch!

- News: https://twitter.com/RIOT_OS and https://fosstodon.org/@RIOT_OS
- For Developers and Users: <https://forum.riot-os.org>
- Support & Discussions on Matrix: <https://matrix.to/#/#riot-os:matrix.org>
- Get the Source Code and Contribute: <https://github.com/RIOT-OS/RIOT>
- Show Cases: <https://www.hackster.io/riot-os>
- Videos on YouTube: <https://www.youtube.com/c/RIOT-IoT>
- Pics: <https://www.flickr.com/people/142412063@N07/>
- Get together at the yearly RIOT Summit: <https://summit.riot-os.org>
- Getting started with a tutorial on <https://riot-os.github.io/riot-course/>



Literature

- *E. Baccelli et al. "RIOT: An open source operating system for low-end embedded devices in the IoT," IEEE Internet of Things Journal, December 2018.*
- *O. Hahm, "Enabling Energy Efficient Smart Object Networking at Internet-Scale," Ecole Polytechnique, December 2016.*
- *O. Hahm, E. Baccelli, H. Petersen, and N. Tsiftes, "Operating Systems for Low-End Devices in the Internet of Things: a Survey," IEEE Internet of Things Journal, October 2016.*
- *D. Lacamera, "Embedded Systems Architecture," O'Reilly, May 2018.*



Source: Pubs and Publications, <https://t1.wp.com/www.bloga.hsa.ed.ac.uk/pubs-and-publications/fitc/2016/10/books.jpg?fit=945>



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