Automatic Pest Detection

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Cloud Computing - Group 3 - 09.02.2023

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Sensor Node - Camera Mounting

- Stable mounting enables blur-free images
- Constant camera frames
- Flexible due to pitch and yaw angle
- Easy to adjust
- Safe and comfortable operation since no permanent touching and holding of single-board computer, ribbon cable and camera module needed
- All connectors remain directly accessible

Sensor Node - Camera Software Setup

- Raspberry Pi OS Bullseye Full 64-bit
- Accessing, configuring and controlling camera by using Python library Picamera2
- Recording and saving pictures repeatedly for YOLO
- Separated from object detection

Sensor Node - Telegram Bot

- active configurable notification system
- recognize and reply to input messages
- add new users automatically
- toggle alert on/off
- input interval with error detection
- sends pictures of rats with counting and confidence

Sensor Node - Object detection

- Yolov5
- Data collection/labeling: Roboflow
 - provided dataset
 - Lucas sister rat pictures
 - ~ **1.500** pictures
- Training:
 - CUDA
 - ~ 200 epochs
- Problems:
 - Pythorch needed Python <= 3.8 -> docker file
 - not compatible with picamera2 (python >= 3.9) -> docker compose with volumes for file exchange

Sensor Node - Object detection



Cluster - General

Requirements:

- Store images which were classified as "Rat"
- Show images which were classified as "Rat"

Therefore we did:

- Create persistent storage to save the images
- Create a WebApp to display the images
- Create a suitable environment on the cluster for the WebApp

Cluster - Virtual Machines

- 3 people working on cluster
- Reduce dependency on hardware
- Simulate Cluster on Raspberries by using Virtual Machines

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RaspberryOS Wasgeschaltet	Name: MasterPi Betriebssystem: Debian (64-bit)	Australistic posters" is can bit failed get mine and control failed and and all allocation and control failed and all all all all all all allocation	Datei Maschine Anzeine Finnahe Geräte Hilfe
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Cluster - Persistent Storage MinIO

• Why?

- Object storage native to Kubernetes
- Binary less than 100MB
- Support of K3S
- \circ Designed for Edge computing
- ...and why not?
 - Pod run. MinIO had repeated crashes
 - Took a long time to come up
 - \circ \quad Worked simultaneously on a diff. solution
 - Problems where hard to fix
 - The oth. solution proved easier to implement

Cluster - Persistent Storage NFS



Cluster - WebApp Environment

Environment to smoothly run the cluster:

- Store images in Repository
 - Kubernetes needs to pull images frequently
 - DockerHub (Already used in manifest)
- Create network services for the WebApp
 - Service kind: "Loadbalancer"
 - Backend and frontend have to be accessible from outside of the cluster

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NAME	TYPE	CLUSTER-IP	EXTERNAL-IP	PORT(S)	AGE
nfs-server	ClusterIP	10.43.184.230	<none></none>	2049/TCP,20048/TCP,111/TCP	21d
mariadb-mariadb	ClusterIP	10.43.184.232	<none></none>	3306/TCP	21d
webapp-client	LoadBalancer	10.43.246.61	192.168.188.23,192.168.188.26,192.168.188.29,192.168.188.31	8080:30880/TCP	21d
webapp-server	LoadBalancer	10.43.177.5	192.168.188.23,192.168.188.26,192.168.188.29,192.168.188.31	5000:30500/TCP	21d
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Architecture



Web-App

- Buildable and runnable with Docker/ Docker-Compose
- Client-Side:
 - Vue open -source JavaScript framework
 - Used for user interface
 - Basic JS services to backend-API to fetch data

Web-App

- Server-Side
 - Express open-source JS framework
 - Used for building APIs
 - Connect to database
 - Fetch data from database and send to frontend
 - Save new detections to database
- Constant consultation with team for interface and cluster-setup

Web App Example



Live Demonstration